



BWN428 Series

**Current Output Dual Axis
Inclinometer**

Technical Manual

V4.0



Introduction

BWN428 is a cost-effective dual-axis inclinometer developed and produced by Bewis Sensing. It adopts MEMS technology and current output. The measurement range is $\pm 90^\circ$, the highest accuracy is 0.02° , and the working temperature is -40°C to $+85^\circ\text{C}$. The product uses a high-precision MEMS accelerometer and a high-resolution differential digital-to-analog converter, with built-in automatic compensation and filtering algorithms, which largely eliminates errors caused by environmental changes. Convert the change of the static gravity field into the inclination change, and directly output the horizontal inclination value through the voltage method. This product has high long-term stability, low temperature drift, simple use, and strong ability to resist external interference. It is a recommended choice to be used for surveying and mapping, industrial automation and other industries.

Features

- Dual axis inclination measurement
- Resolution: 0.001°
- Power supply: 12-36V
- Dimension: L90*W40.5*H26 (mm)
- Highest accuracy: 0.02°
- Range: $\pm 90^\circ$
- Output mode : 4-20mA/0-20mA/0-24mA optional
- IP67 Protection level

Application

- Industrial automatic leveling
- Medical instruments
- Photovoltaic automatic tracking
- Tower tilt monitoring
- Lifting equipment inclination control
- Structural deformation monitoring
- Surveying and Mapping Instruments
- Equipment automation

Product Feature



Electrical index

Parameter	Condition	Minimum	Typical	Maximum
Power voltage(V)		12		36
Working Current (mA)	No load	20	50	60
Output load (Ω)	Max			500
Operating Temperature ($^{\circ}\text{C}$)		-40	25	85
Storage Temperature ($^{\circ}\text{C}$)		-55	25	100



Performance index

Measurement Range ($^{\circ}$)	Condition	± 90
Measurement axis	X-Y	
Accuracy ($^{\circ}$)	Highest	0.02
Resolution ($^{\circ}$)	Completely still	0.001
Zero bias ($^{\circ}/^{\circ}\text{C}$)	-40~85 $^{\circ}\text{C}$	± 0.01
Cross axis error($^{\circ}$)	0.02	
Output frequency (Hz)	100	
Current output at zero(mA)	10(0-20); 12(4-20); 12(0-24)	
Full-scale output current range (mA)	4-20 (0-20optional) (0-24 optional)	
Mean time between failures MTBF	≥ 90000 h	
Electromagnetic compatibility	According to GBT17626	
Insulation resistance	≥ 100 M Ω	
Impact resistance	2000g, 0.5ms, 3 times/axis	

Resolution: The smallest change value of the measured value that the sensor can detect and distinguish within the measurement range.

Accuracy: The root mean square error of the actual angle and the sensor measuring angle for multiple (≥ 16 times) measurements



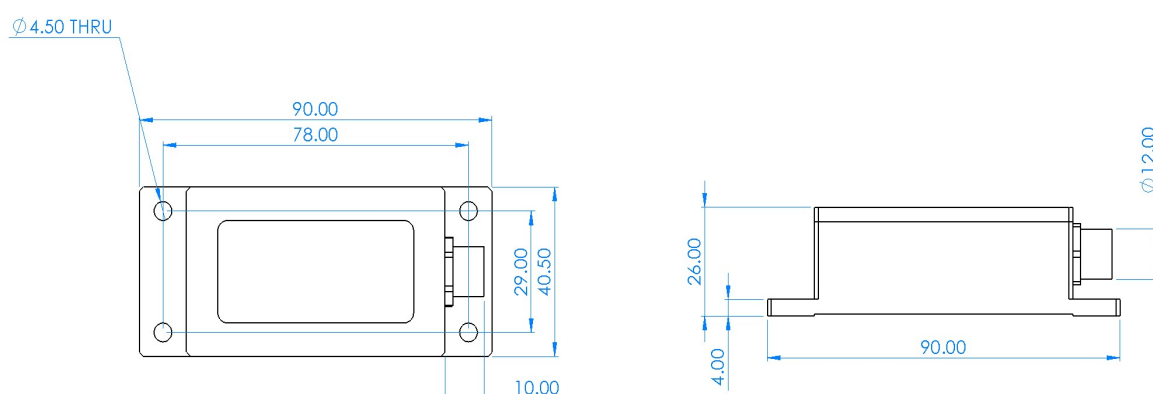
Mechanical Index

Connector	Metal Joint (Cable 1.5m)
Protection level	IP67
Shell material	Magnesium aluminum alloy oxidation
Installation	Four M4 screws



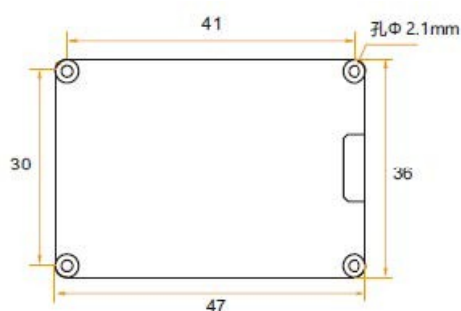
Package product size

Product size: L90*W40.5*H26 (mm)



Bara board product size

Product size: L47*W36*H15 (mm), the length and width may be an error of 1mm, please refer to the actual products

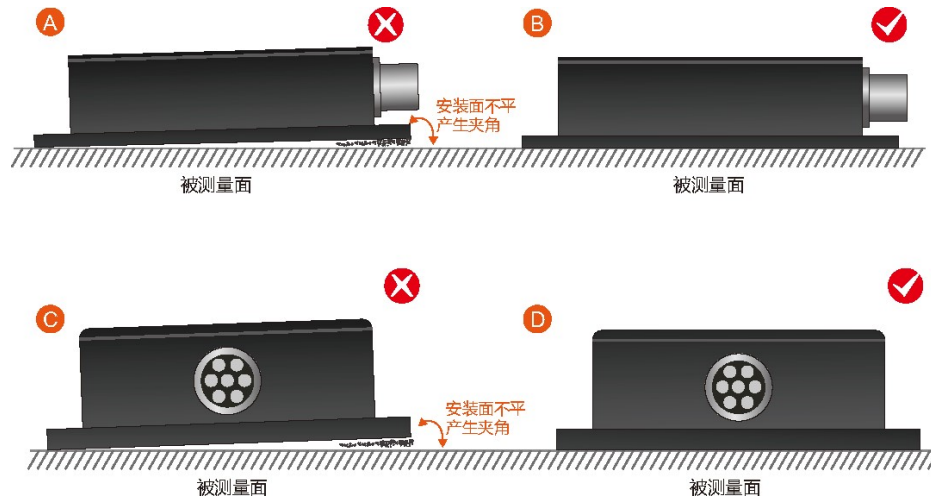




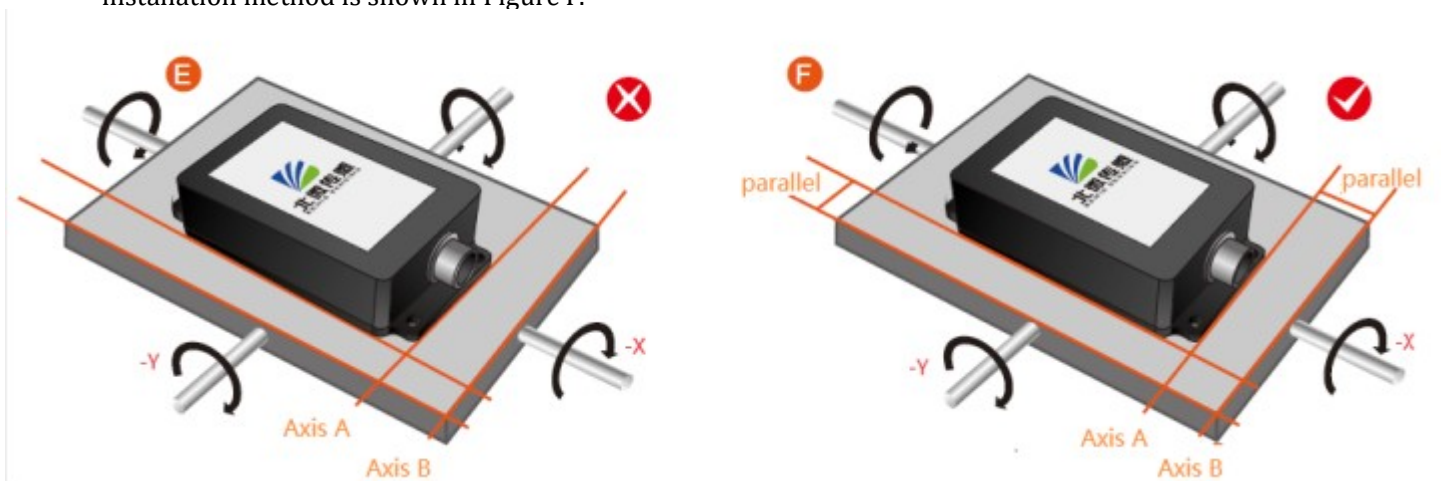
Installation

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible, and there should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.



Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.

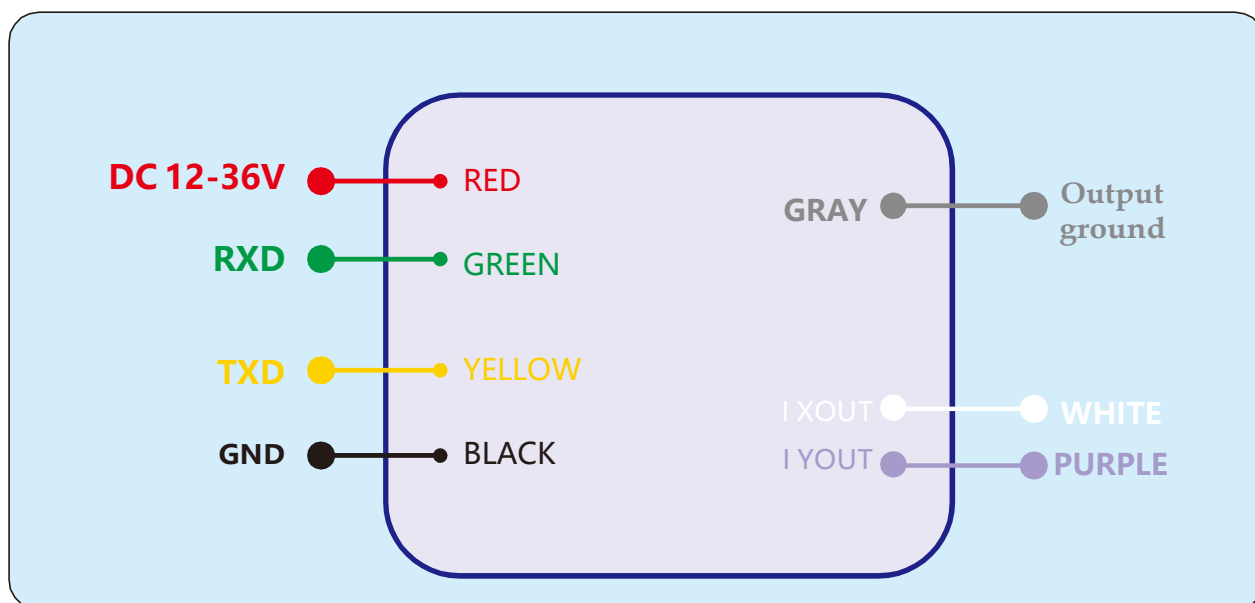


Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.

Electrical Interface

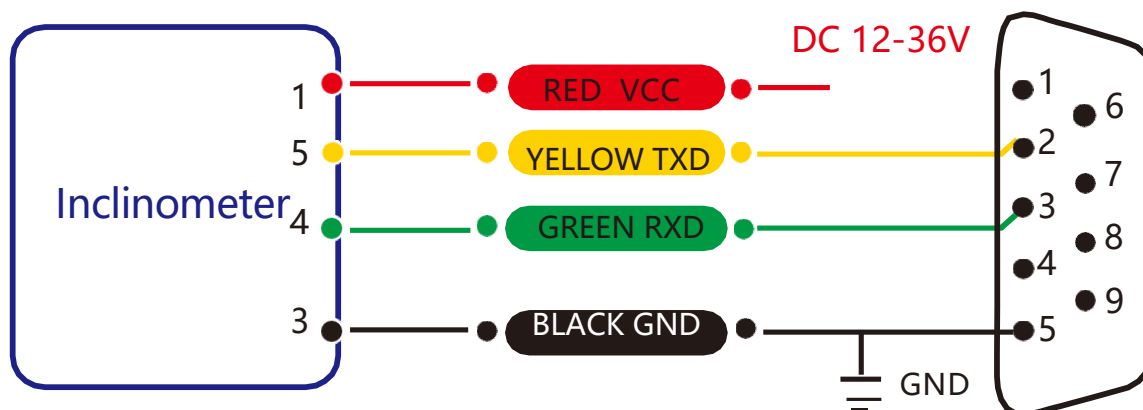
Electrical interfaces

Cable color & Function	RED	BLACK	GREEN	YELLOW	WHITE	PURPLE	GRAY
	1	3	4	5	6	7	10
	VCC DC 12-36V	GND	RXD	TXD	I XOUT	I YOUT	Output ground



Electrical interfaces

Cable color & Function	RED	BLUE	BLACK	GREEN	YELLOW
	1	2	3	4	5
	VCC DC 12-36V	NC	GND	RXD	TXD



RS 232 wiring diagram

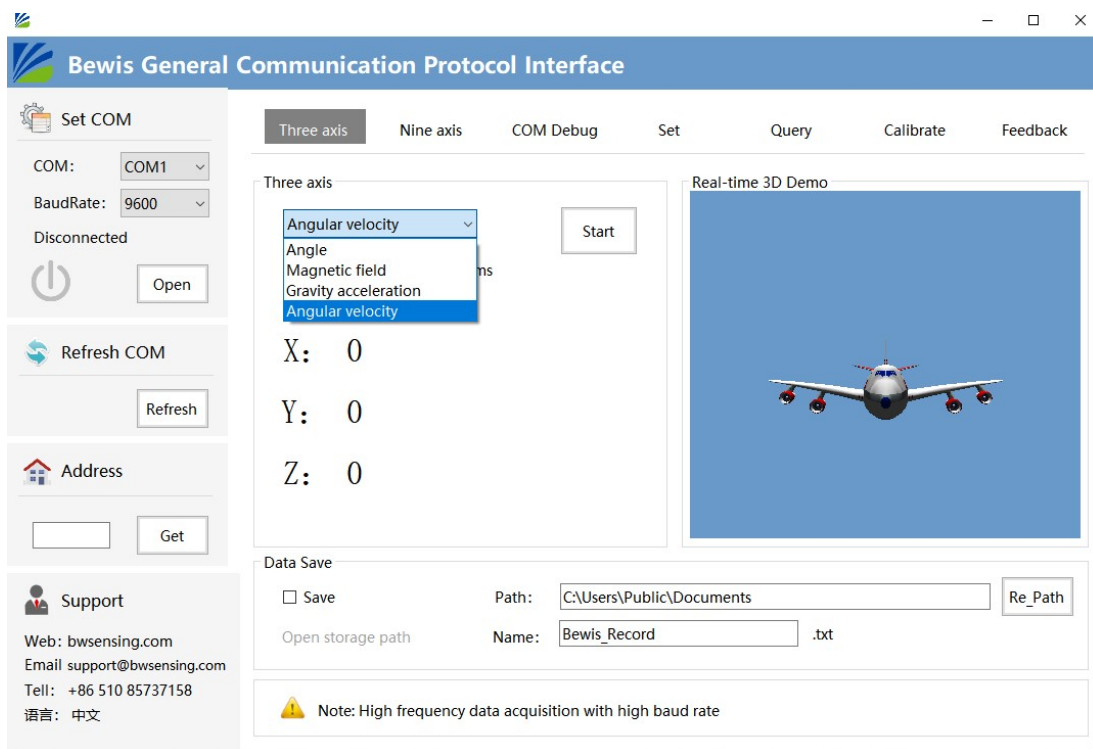
Debugging software

You can download the serial debugging assistant directly on the official website (technical service -> download area), or you can use the more convenient and intuitive host computer software.

BWN428 supporting serial port debugging software can connect the inclination sensor on the computer to display the angle. The software debugging interface is shown in the figure below. Using the tilt angle to debug the host computer, you can conveniently display the current X direction and Y direction tilt angle, and you can also modify and set other parameters.

Step:

- ① Connect the serial port hardware of the inclinometer correctly, and connect the power supply.
- ② Select computer serial port and baud rate and click connect serial port.
- ③ Click start button and the current inclination Angle of the incliner in X and Y directions will be displayed on the screen.



Order information

Model	Communication mode	Package situation
BWN428-90-420	4-20mA Current/RS232	IP67 Package/Metal joint
BWN428-90-020	0-20mA Current/RS232	IP67 Package/Metal joint
BWN428-90-024	0-24mA Current/RS232	IP67 Package/Metal joint

Executive standard

- Specification for Static Calibration of Biaxial Inclination Sensors National Standard (Draft)
- GB/T 191 SJ 20873-2003 General Specification for Tiltmeters and Levels

BWN428 Series

Current Output Dual Axis Inclinometer

Wuxi Bewis Sensing Technology LLC

Add: Building 30, NO. 58, Xiuxi Road, Binhu District,
Wuxi City, Jiangsu Province, China

Tel: +86 18921292620

Mail: sales@bwsensing.com

Web: www.bwsensing.com