



LoRaWAN LWHD-WM420 Long-distance wireless inclinometer **Technical Manual**



LoRaWAN Series Long-distance wireless transmission inclinometer



Introduction

LoRaWAN LWHD-WM420 long-distance wireless transmission inclinometer is designed for structural health monitoring (SHM). It can be used for up to 10 years (In condition of sending data every hour). Data can be uploaded through the LoRaWAN G500 gateway (optional accessory) connected to TTN or Chirpstack and APP server.

All modules are designed with ultra-low power consumption, the sleep current is lower than 4µA, and have timed wake-up and motion detective wake-up functions. Working temperature is -40 °C \sim +85 °C.

Main Feature

- Accuracy: 0.05°
- LoRaWAN Wireless network, star network
- Battery life up to 10 years*
- 4PCS NdFeB strong magnetic screws (optional) Can be quickly installed on any iron surface to start work
- Resolution 0.001°
- Dual axis inclination measurement, range ±90°
- More user-friendly design, more in line with actual deployment requirements on site

Functions

- Working frequency 868/915/923, etc MHz for optional
- Built-in ROM to automatically save timestamped data in case of poor signal
- The built-in ROM can save up to 60,000 sets of data (20Bytes per set of data)
- Automatic sleep

- Small size, light weight, easy installation
- It can be connected to an Android phone through OTG USB Type-C, and using the APP for parameter configuration and data reading
- Temperature output
- Timed wakeup, Vibration wakeup

Note: * means under laboratory conditions



Application

- Dangerous housing monitoring
- Bridge tower inclination measurement
- Dam monitoring
- Slope disaster prevention

- Ancient building protection monitoring
- Tunnel monitoring
- Foundation pit monitoring
- Tower tilt monitoring

Product Feature

🗭 Mechanical Index

| Connector | Aviation connector |
|---|---------------------------|
| Protection level | IP68 (1m underwater, 24h) |
| Shell material Magnesium aluminum alloy anodizing | |
| Installation | Four M6 screws |

🗙 Performance Index

| | Measuring range(°) | 0~±90 | | |
|---|---------------------------------|---|--|--|
| | Measuring axis | X-Y | | |
| - | Accuracy(°) | At room temperature 0.05 | | |
| | Resolution(°) | Completely stationary 0.001 | | |
| | Zero temperature drift(°/°C) | -40°C∽+85°C ±0.001 | | |
| | Cross-axis error(°) | At room temperature 0.008 | | |
| Output frequency (Hz) | | Up to 10 (Connect Android Phone or PC via cable), Up to 0.1 (via LoRaWAN) | | |
| | Auto-sleep mode | Support | | |
| Timed Wake-up Movement Detected Wake-up Mean Time Between Failure | | Support | | |
| | | Support | | |
| | | 100,000 hours | | |
| | Electromagnetic compatibility | Accordance to GBT17626 | | |
| | Insulation resistance | ≥100 MΩ | | |
| | Impact-resistant | 2000g, 0.5ms, 3Times/axis | | |
| | Size (mm) | L109*W88*H63mm (without antenna) L109*W88*H131mm (with radome) | | |
| | Weight (g) | 550 (±10) (with two batteries) | | |

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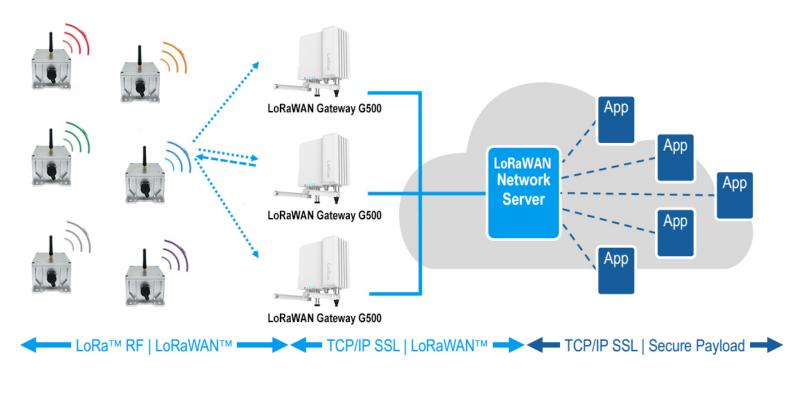
Resolution: The smallest change value of the measured value that the sensor can detect and distinguish within the measurement range.

Accuracy: The root mean square error of the actual angle and the sensor measuring angle for multiple (≥16 times) measurements.

🗭 Electrical Index

| | Power voltage | 3.6VDC~5VDC | |
|------------------------|---|--------------|--|
| Power | Working current | 100mA (Peak) | |
| | Stand-by current | 4μΑ | |
| | Battery capacity 3.6V 8500mAh*2 / 3.6V 7700mAh*2(Optional) | | |
| Communication distance | Maximum: 15Km | | |
| Data frame | 20Bytes or 36Bytes(extra included three-axis acceleration) | | |
| Reliability | Reliability Reliability The mean time between failures (MTBF) is not less than 100,000 hours Ultra-low power consumption design, including automati sleep mode, timing wake-up, sports wake-up | | |

Network topology



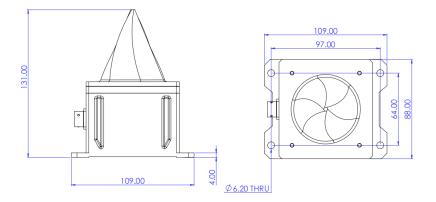
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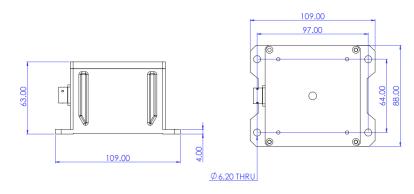


Package product size

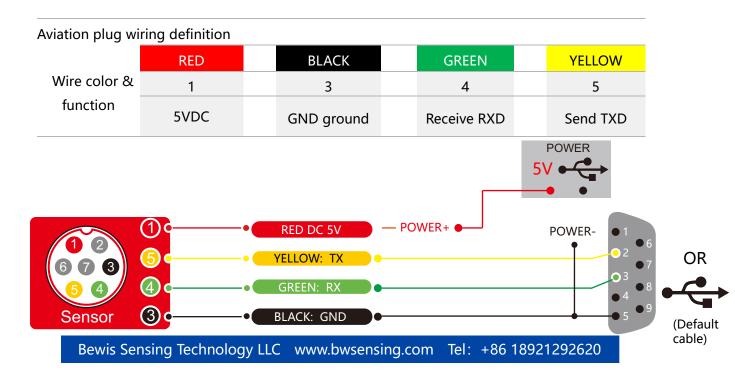
Product size: L109*W88*H131mm (with radome)



Product size: L109*W88*H63mm (without antenna)



Electrical Interface

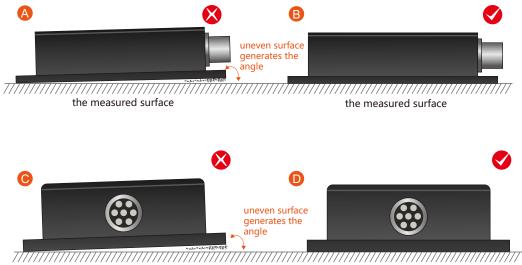




Installation

This series of products can only be installed vertically (pendulum type measurement), not horizontally. The correct installation method can avoid measurement errors. The following points should be done when installing the sensor:

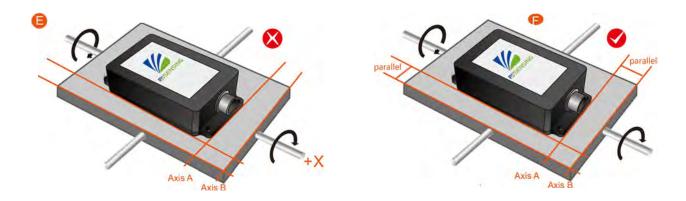
First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible, and there should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.



the measured surface

the measured surface

Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.



Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.



Packing list



LWHD-WM400 *1PC



EVE ER26500 *2PCS



SAFT ER26500 *2PCS (Optional)



3D printed radome *1PC (Optional)



5cm 2dBi antenna *1PC Two types of antennas can be choosed to meet the needs of frequency band switching (848-888MHz) or (895-935MHz)



9cm 2.5dBi antenna *1PC(Optional) Two types of antennas can be choosed to meet the needs of frequency band switching (848-888MHz) or (895-935MHz)



Aviation plug-USB Power&Data 2in1 cable *1PC



NdFeB strong magnetic screws *4PCS (Optional)



OTG USB Type-A to Type-C *1PC



Executive standard

- Enterprise Quality System Standard: ISO9001:2015 Standard (Certificate
- No.064-21-Q-3290-RO-S)
- CE certification (certificate number: M.2019.103. U Y1151)
- ROHS (certificate Number: G 190930099)
- GB/T 191 SJ 20873-2003 General specification for inclinometer and level
- GBT 18459-2001 The calculation method of the main static performance index of the sensor
- JJF 1059.1-2012 Evaluation and expression of measurement uncertainty
- •GBT 14412-2005 Mechanical vibration and shock Mechanical installation of accelerometer
- GJB 450A-2004 General requirements for equipment reliability
- GJB 909A Quality control of key parts and important parts
- GJB899 Reliability appraisal and acceptance test
- GJB150-3A High temperature test
- GJB150-4A Low temperature test
- GJB150-8A Rain test
- GJB150-12A Sand and dust experiment
- GJB150-16A Vibration test
- GJB150-18A Impact test
- GJB150-23A Tilt and rock test
- GB/T 17626-3A Radio frequency electromagnetic field radiation immunity test
- GB/T 17626-5A Surge (impact) immunity test
- GB/T 17626-8A Power frequency magnetic field immunity test
- GB/T 17626-11A Immunity to voltage dips, short-term interruptions and voltage changes
- GB/T 2423.22-2012 Environmental Test Part 2: Test Method Test N: Temperature Change (IEC 60068-2-14:2009, IDT)
- GB/T 10125-2012 Artificial atmosphere corrosion test Salt spray test (ISO 9227:2006,IDT)

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