



# **BW-VG125C Series**

**Low-cost CAN**

**Dynamic Inclinometer**

## **Technical Manual**

V3.0



## Introduction

The VG125C Dynamic Inclination Sensor product is a low cost attitude measurement device that measures the inertial attitude parameters of roll and pitch as well as angular velocity and acceleration of a moving carrier. Attitude deviations are estimated by a 6-state Kalman filter with appropriate gain for inclination measurements in motion or vibration. The VG125C utilizes high quality and reliable MEMS accelerometers and gyroscopes with algorithms to ensure measurement accuracy, and a hermetically sealed design and rigorous workmanship to ensure that the product can accurately measure the carrier's attitude parameters even in harsh environments. The VG125C is equipped with a digital interface, which makes it very easy to be integrated into the user's system.

## Main Feature

- Dynamic accuracy: 1°
- Static accuracy: 0.01°
- Non-linear compensation, quadrature compensation
- Special offset tracking algorithm to eliminate drift
- CAN interface output
- Wide temperature range: -40℃~+85℃
- High-performance Kalman filter algorithm
- Dimension: L60x W59 x H29 (mm)

## Application

- Underwater unmanned boat
- Turbine sloshing monitoring
- Platform stability
- large ship
- Photoelectric pod
- Unmanned Drive
- Special Vehicles
- Unmanned Craft

## Product Feature



### Electrical indicators

Voltage	9-36V DC
Working current	30mA (40mA Max)
Temperature in use	-40~85°C
Temperature in store	-55~100°C



### Performance Index

Attitude Parameter	Dynamic accuracy	1°
	Static accuracy	0.01°
	Resolution	0.01°
	Tilt margin	Pitch $\pm 90^\circ$ , roll $\pm 180^\circ$
Physical properties	Dimension	L60×W59×H29 (mm)
	Weight (with wire)	280g
	Weight (With packaging)	360g
Interface characteristics	Start delay	<50ms
	Maximum sampling rate frequency	500Hz
	Serial communication rate	2400 to 115200 baud rate
	Digital output format	Binary high-performance protocol
Trouble-free work on average	$\geq 30000$ hours	
EMC	According to GBT17626	
Insulation Resistance	$\geq 100M\Omega$	
Surge suppression	2000g, 0.5ms, 3 Time/shaft	

**Resolution:** The measured minimum change value that the sensor can detect and resolve within the measurement range.

**Accuracy:** The error between the actual angle and the Root mean square(RMS) of the measured angle of the sensor( $\geq 16$  times).



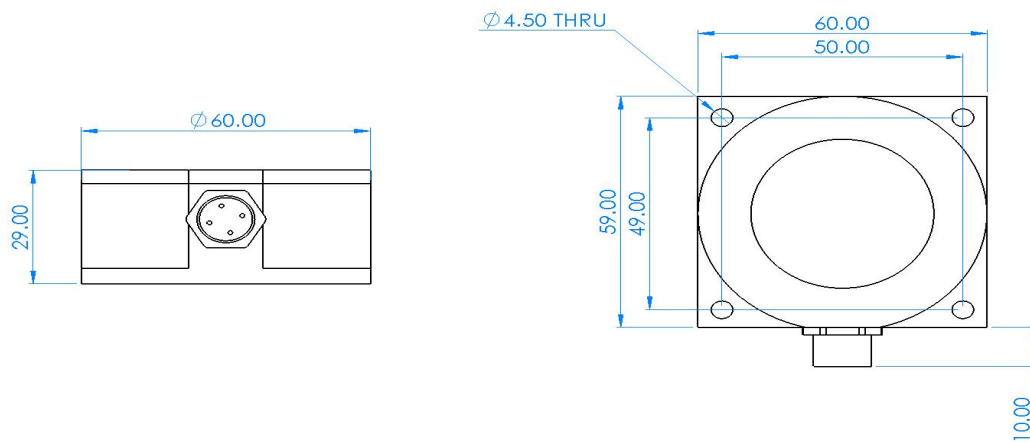
## Mechanical

Connector	Metal interface (Cable 1.5m)
Protection level	IP67
Shell material	Magnesium aluminum alloy oxidation
Installation	Four M4 screws



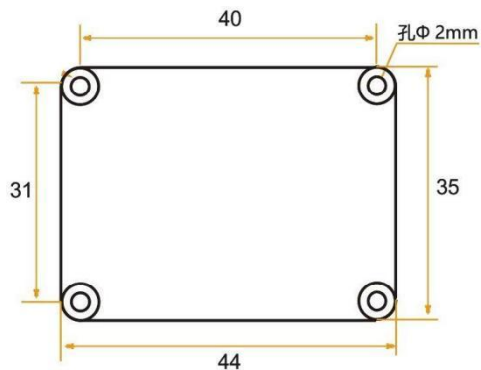
## Package product size

Product Size: L60\*W59\*H29 (mm)



## Bare board product size

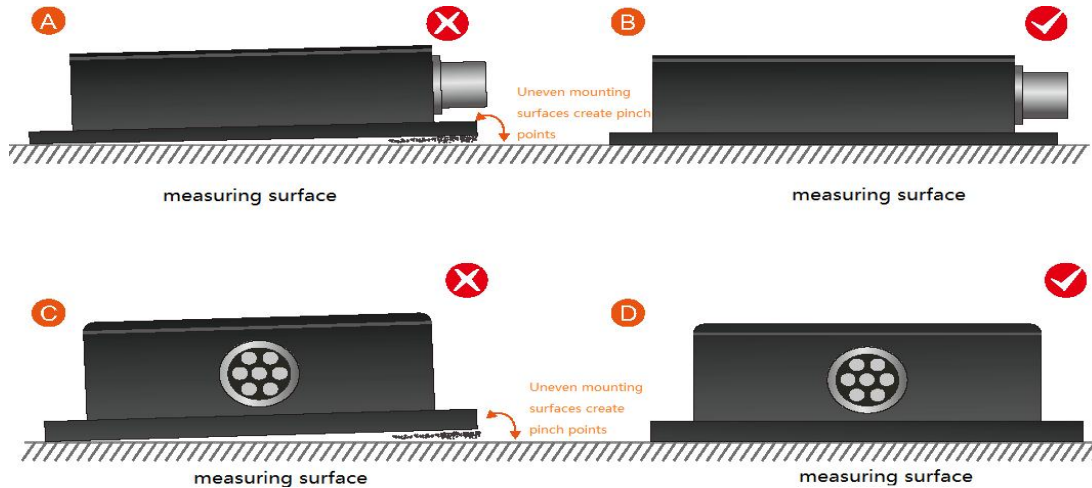
PCB Size: L44\*W35\*H11mm,  $\pm 1$ mm error for length and width dimensions, please refer to actual size



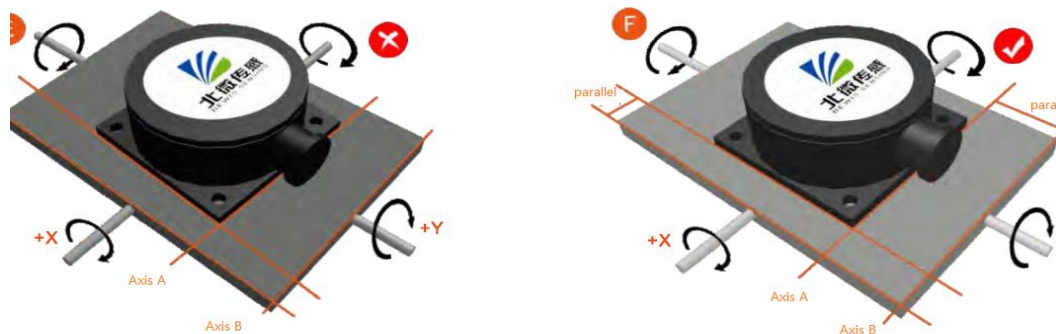
## Installation

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible. There should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.



Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.

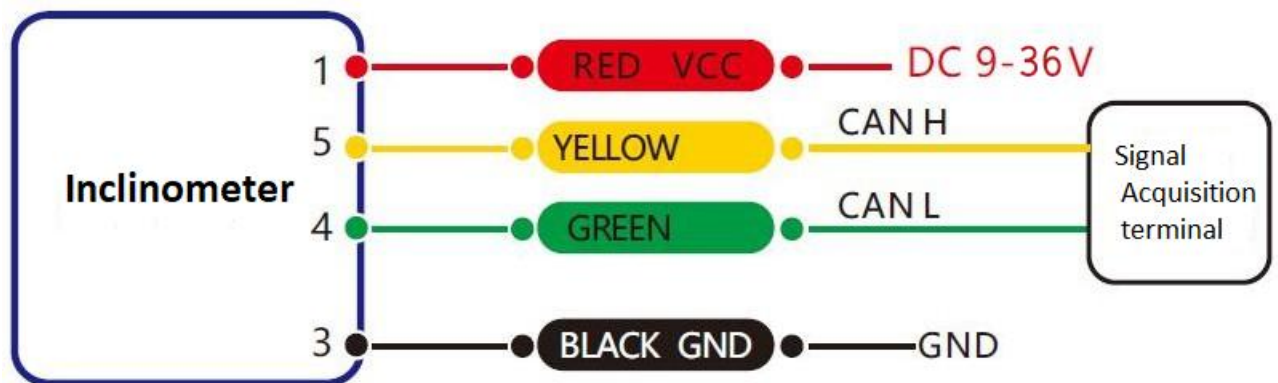


Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.

## Electrical Interface

### Wiring Definitions

Line Color	红色RED	蓝色BLUE	黑色BLACK	绿色GREEN	黄色YELLOW
Function	1	2	3	4	5
	VCC DC 9-36V	NC	GND地	CAN L	CAN H



CAN bus wiring diagram

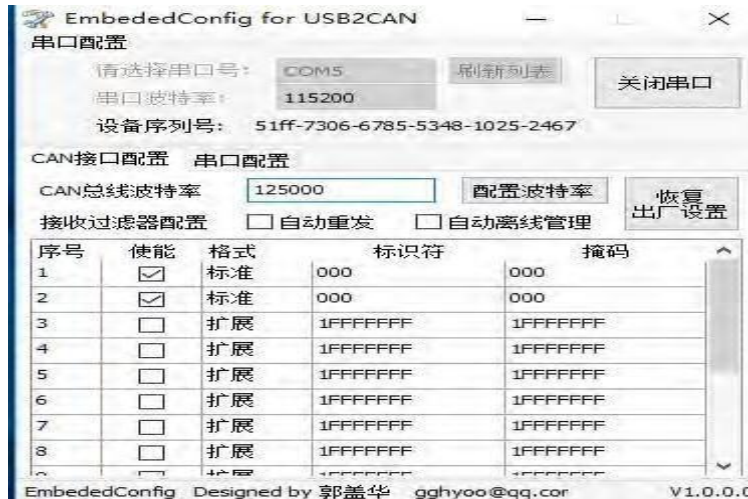


## Testing software

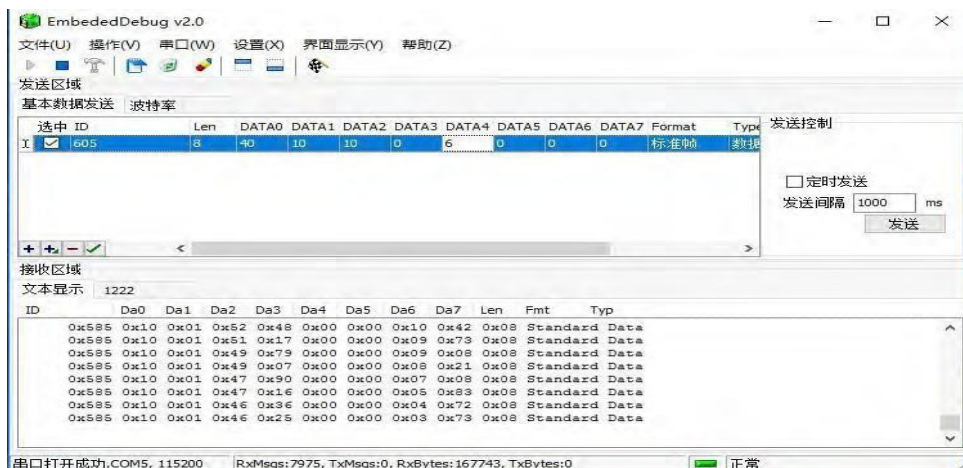
Since there is generally a dedicated CAN receiving device for data communication with CAN interface products, it is the software that comes with the CAN acquisition device, and the usage methods are different, so there is no corresponding supporting software. Below is the CAN receiving module and product communication used by our company as an example:



Configure CAN baud rate and parameters as follows:



The receiving and sending area are set as follows:



## Order Information

Model	Communication Mode	Package Situation
BW-VG125C	CAN	IP67/ Metal interface

## Executive standard

- National Standard for Static Calibration of Biaxial Inclination Sensors (Draft)
- GB/T 191 SJ 20873-2003 General Specification for Tiltmeters and Leveling DevicesCE certification (certificate number: M.2019.103. U Y1151)



# **BW-VG125C Series**

**Low-cost CAN Dynamic Inclinometer**

## **Wuxi Bewis Sensing Technology LLC**

Add: Building 30, NO. 58, Xiuxi Road, Binhu District, Wuxi City,  
Jiangsu Province, China

Tel: +86 18921292620

Mail: [sales@bwsensing.com](mailto:sales@bwsensing.com)

Web: [www.bwsensing.com](http://www.bwsensing.com)