



BW-VG225 Series

**Low Cost CAN Bus Dynamic
Inclination Sensor**

Technical Manual



Introduction

The VG225 Dynamic Inclination Sensor product is a low cost attitude measurement device that measures the inertial attitude parameters of roll and pitch as well as angular velocity and acceleration of a moving carrier. Attitude deviations are estimated by a 6-state Kalman filter with appropriate gain for inclination measurements in motion or vibration. The VG225 utilizes high quality and reliable MEMS accelerometers and gyroscopes with algorithmically guaranteed accuracy, while the sealed design and rigorous workmanship ensures that the product can accurately measure the carrier's attitude parameters even in harsh environments. The VG225 is equipped with digital interface, which makes it easy to be integrated into the user's system.

Feature

- Non-linear compensation, quadrature compensation
- Dynamic and static measurement
- Gyro drift compensation
- Special offset tracking algorithm to eliminate drift
- CAN bus output
- Wide temperature range: $-40^{\circ}\text{C} \sim +85^{\circ}\text{C}$
- High-performance Kalman filter algorithm
- Small Size: L55 x W37 x H24 (mm)

Application

- Marine vessels
- Construction Machinery
- Platform stability
- Agricultural machinery
- ROV underwater robot navigation
- Unmanned Drive
- Robot
- Unmanned Craft

Feature



Electrical indicators

Voltage	9-36V DC
Working current	30mA (40mA Max)
Temperature in use	-40~85°C
Temperature in store	-55~100°C



Performance Index

Attitude Parameter	Dynamic Accuracy	0.5°
	Static Accuracy	0.01°
	Resolution	0.01°
	Tilt range	Pitch $\pm 90^\circ$, Roll $\pm 180^\circ$
Physical properties	Dimension	L60×W59×H29(mm)
	Weight (with cable)	280g
	Weight (with package)	360g
Interface characteristics	Start-up delay	<50ms
	Maximum Output Frequency	500Hz
	Serial Communication Rate	2400 to 115200 baud rate
	Digital Output Format	Binary High Performance Protocol
Trouble-free work on average	≥ 90000 hours	
EMC	According to GBT17626	
Insulation Resistance	$\geq 100 \text{ M}\Omega$	
Surge suppression	2000g, 0.5ms, 3 Time/shaft	

Resolution: The smallest change in the measured value that the sensor can detect and distinguish within the measurement range.

Accuracy: The root mean square error between the actual angle and the angle measured by the sensor for multiple times (≥ 16 times).



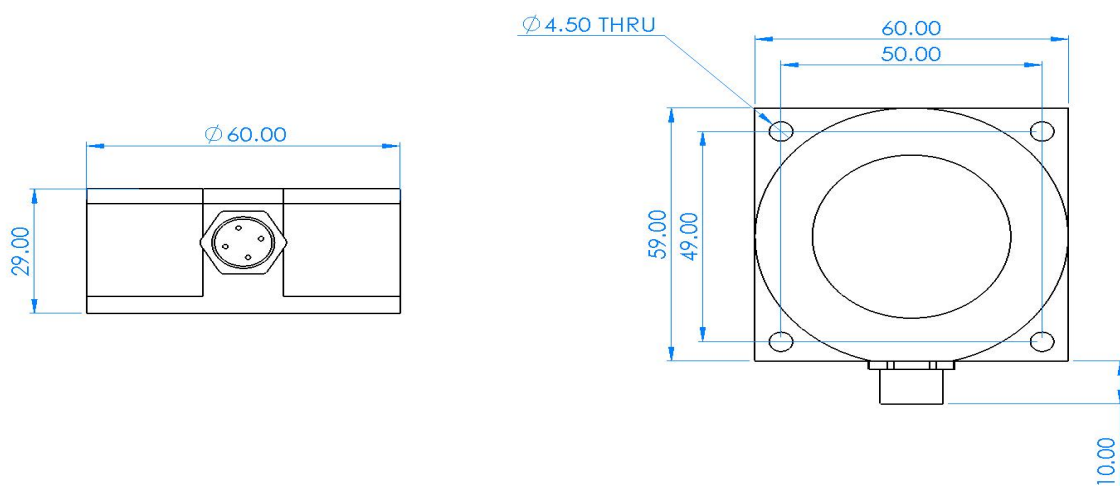
Mechanical properties

Connector	Metal interface (Cable 1.5m)
Protection level	IP67
Shell material	Magnesium aluminum alloy oxidation
Installation	Four M4 screws



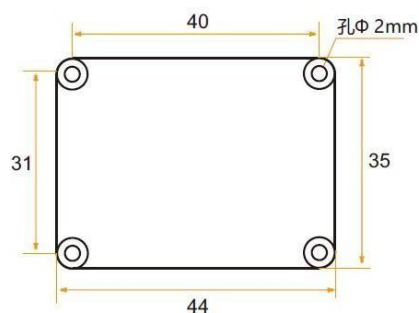
Package product size

Product Size: L60*W59*H29 (mm)



Bare board product size

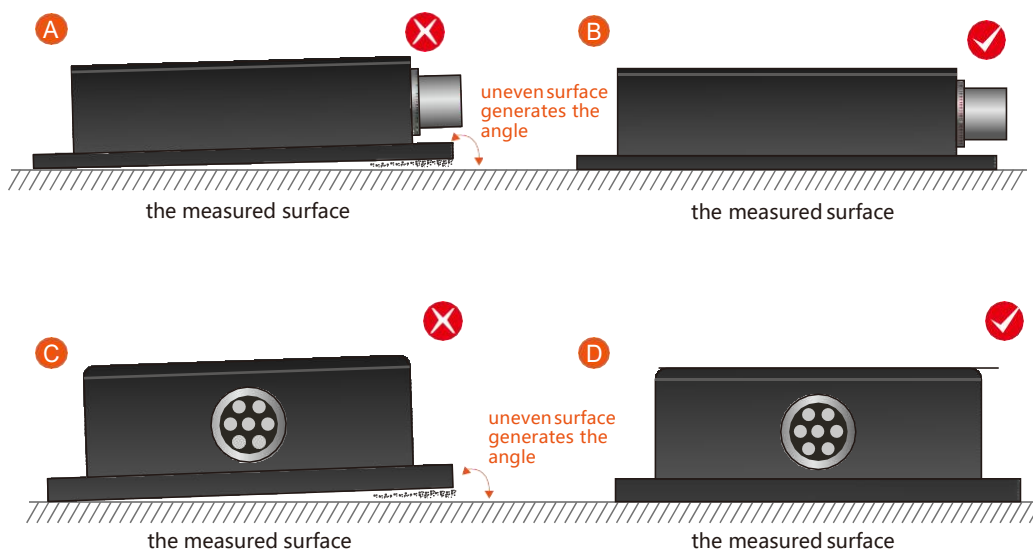
Product Size: L44*W35*H11 (mm) The length and width may have an error of ± 1 mm, please refer to the actual product



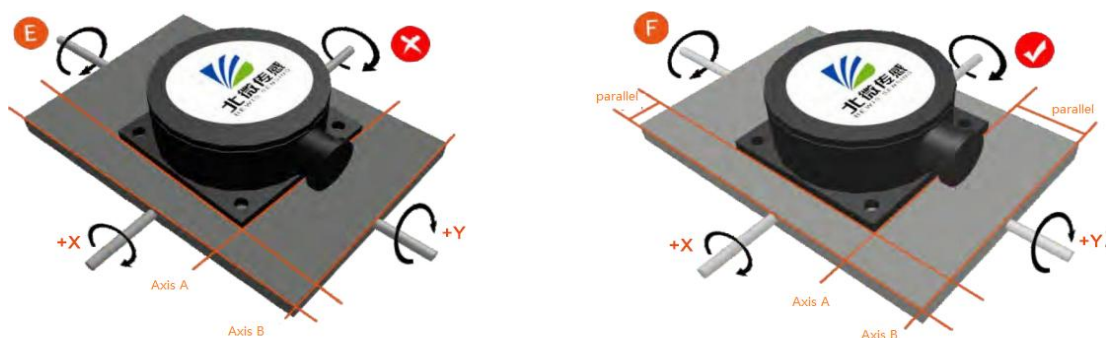
Installation

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible. There should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.



Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.

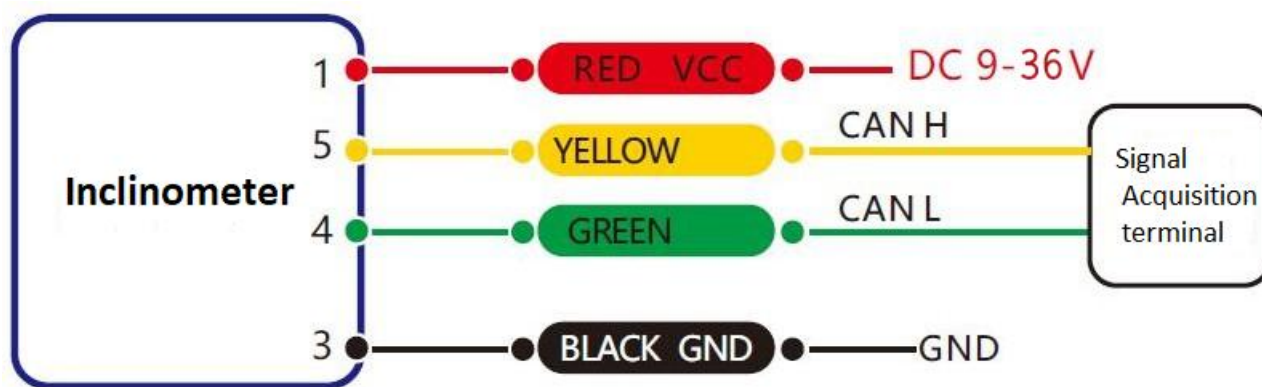


Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.

Electrical Interface

Wiring definition

	RED	BLUE	BLACK	GREEN	YELLOW
Line Color	1	2	3	4	5
Function	VCC DC9-36V	NC	GND	CAN L	CAN H



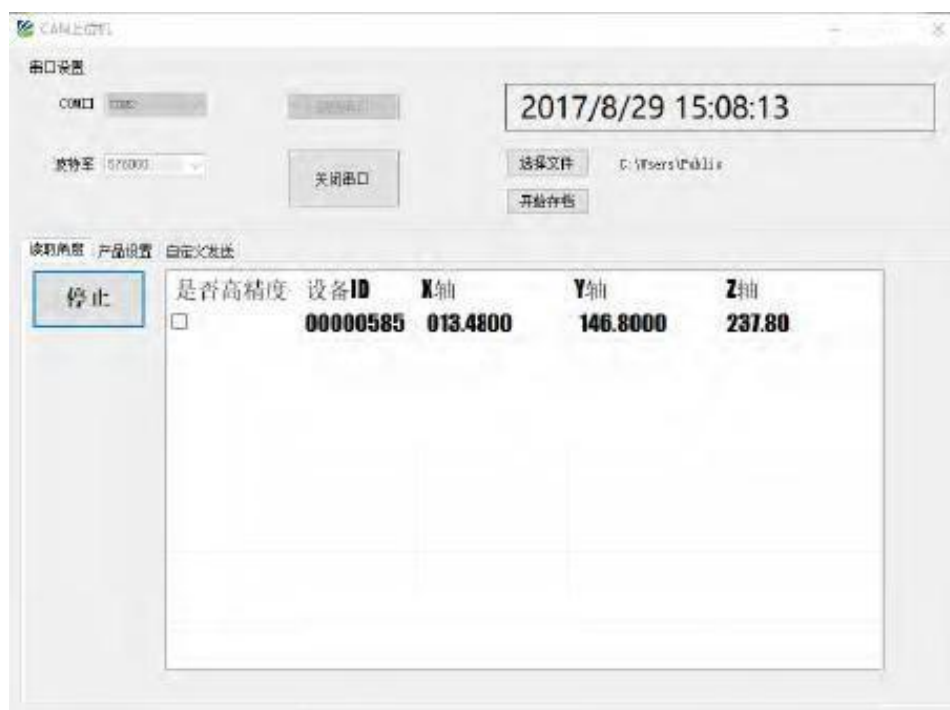
CAN bus wiring diagram

Testing software

You can download the serial debugging assistant directly on the official website (technical service -> download area), or you can use the more convenient and intuitive host computer software. The BW-VG125 supporting serial port debugging software can connect the inclination sensor on the computer to display the angle. The software debugging interface is shown in the figure below. Using the tilt angle to debug the host computer, you can easily display the current X and Y directions, and you can also modify and set other parameters.

Step:

- ① Connect the serial port hardware of the inclinometer correctly, and connect the power supply.
- ② Select correct device Type (Select Azimuth series).
- ③ Select computer serial port and baud rate and click connect serial port.
- ④ Click start button and the current inclination Angle of the incliner in X and Y directions will be displayed on the screen.



Order Information

Model	communication mode	Package situation
BW-VG225-CAN	CAN	IP67/ Metal interface

Executive standard

- Specification for Static Calibration of Biaxial Inclination Sensors National Standard (Draft)
- GB/T 191 SJ 20873-2003 General Specification for Tiltmeters and Levels

BW-VG225 Series

Low-cost CAN Dynamic Inclinometer

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