BW-VG625 Series

Ultra High Accuracy CAN Dynamic Inclination Sensor

Technical Manual

V3.0

Introduction

The VG625 dynamic inclinometer is a high-precision attitude measurement device that can measure the roll, pitch and angle of moving carriers. Inertial attitude parameters for velocity and acceleration. The attitude deviation is estimated by the 6-state Kalman filter with appropriate gain, which is suitable for operation. Inclination measurement under dynamic or vibrating conditions. VG625 uses high-quality and reliable MEMS accelerometer and gyroscope, and passes algorithms. The measurement accuracy is ensured, while the sealing design and strict process ensure that the product can accurately measure the attitude parameters of the carrier in the harsh environment. Pass through various compensations such as nonlinear compensation, quadrature compensation, temperature compensation and drift compensation, it can greatly eliminate the error caused by interference and improve the level of accuracy of the product.

VG625 has a digital interface, which can be easily integrated into the user's system.

Feature

- Dynamic accuracy: 0.05°
- Static accuracy: 0.01°
- Non-linear compensation, quadrature compensation
- Special offset tracking algorithm to eliminate drift
- CAN interface output optional
- Wide temperature range：-40℃～+85℃
- High-performance Kalman filter algorithm
- Dimension：L60x W59 x H29（mm）

Application

- Underwater unmanned boat
- Turbine sloshing monitoring
- Platform stability
- large ship
- Photoelectric pod
- Unmanned Drive
- Special Vehicles
- Unmanned Craft

Feature

⚡ Electrical index

Voltage	9-36V DC
Working current	30mA （40mA Max)
Temperature in use	-40~85℃
Temperature in store	-55~100℃

🔧 Performance Index

Attitude Parameter	Dynamic accuracy	0.05°
	Static accuracy	0.01°
	Resolution	0.01°
	Tilt margin	Pitch ± 90º, Roll ± 180º
Physical properties	Dimension	L60×W59×H29 （mm)
	Weight (with wire)	280g
	Weight (With packaging)	360g
Interface characteristics	Start delay	<50ms
	Maximum sampling rate frequency	500Hz
	Serial communication rate	2400 to115200 baud rate
	Digital output format	Binary high-performance
Trouble-free work on average	≥30000 hours	
EMC	According to GBT17626	
Insulation Resistance	≥100MΩ	
Surge suppression	2000g， 0.5ms， 3 Times/shaft	

Resolution：The measured minimum change value that the sensor can detect and resolve within the measurement range.
Accuracy: The error between the actual angle and the Root mean square(RMS) of the measured angle of the sensor(≥16 times).
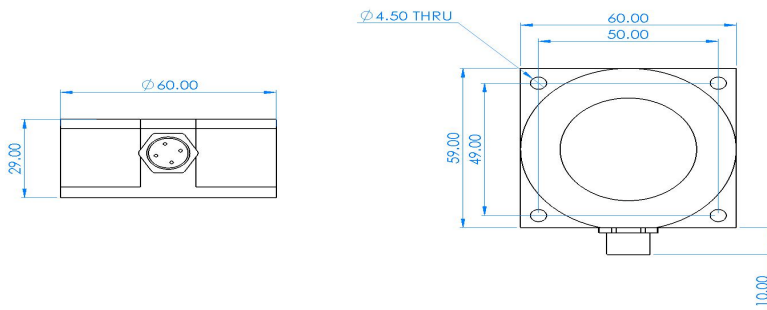
Mechanical

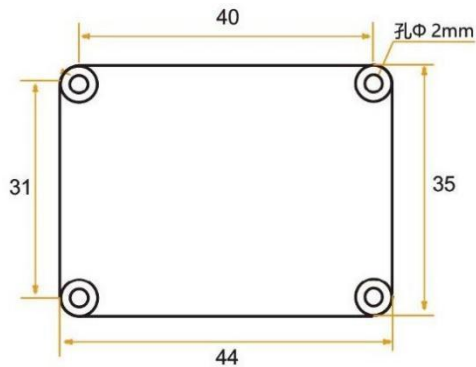|	
Connector	Metal interface (Cable 1.5m)
Protection level	IP67
Shell material	Magnesium aluminum alloy oxidation
Installation	Four M4 screws

Package product size

Product Size: L60*W59*H29 (mm)

Bare board product size

PCB Size: L44*W35*H11mm, ±1mm error for length and width dimensions, please refer to actual size

Installation

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible. There should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.
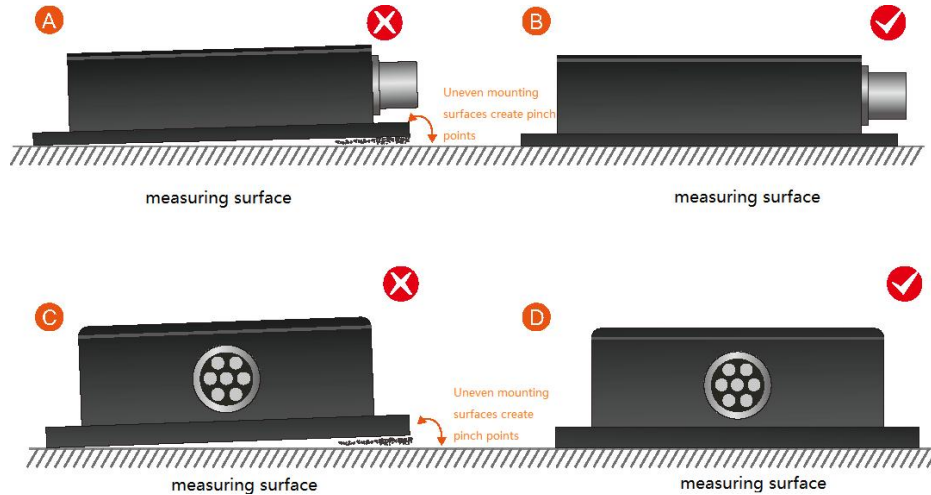
Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.
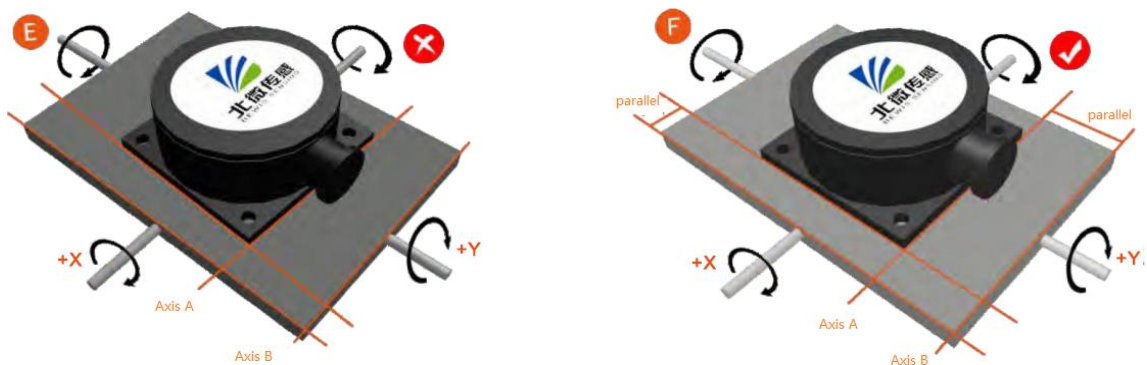
Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.

electrical connection

Wiring Definitions

	红色RED	蓝色BLUE	黑色BLACK	绿色GREEN	黄色YELLOW
Line Color	1	2	3	4	5
Function	VCC DC 9-36V	NC	GND ground	CAN L	CAN H

CAN bus wiring diagram
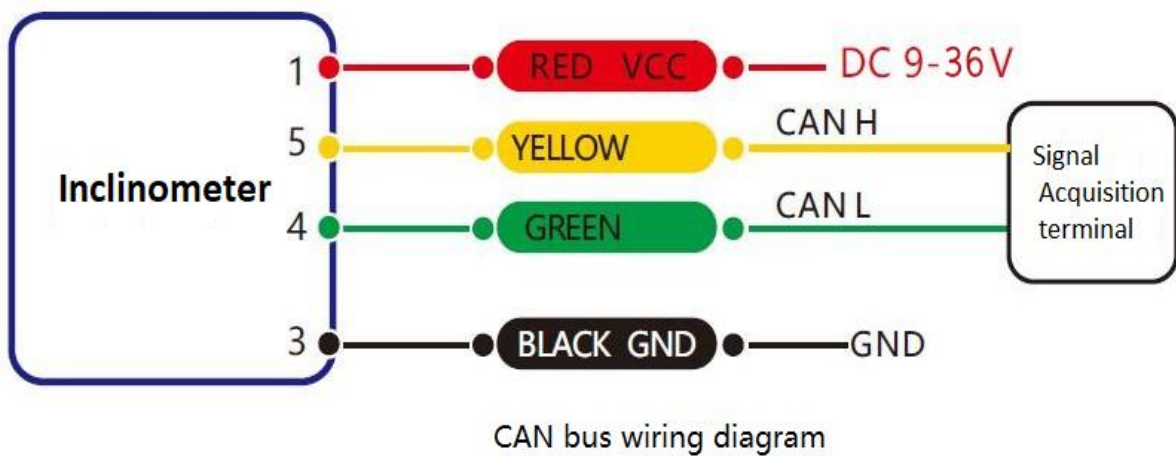
Debugging software

When communicating with CAN interface products, there is generally a dedicated CAN receiving device, so the software comes with the CAN acquisition device. The usage methods are different, so there is no corresponding supporting software. Take the CAN receiver module and product communication used by our company as an example below:

Configure CAN baud rate and parameters as follows:

The receiving and sending area is set as follows:
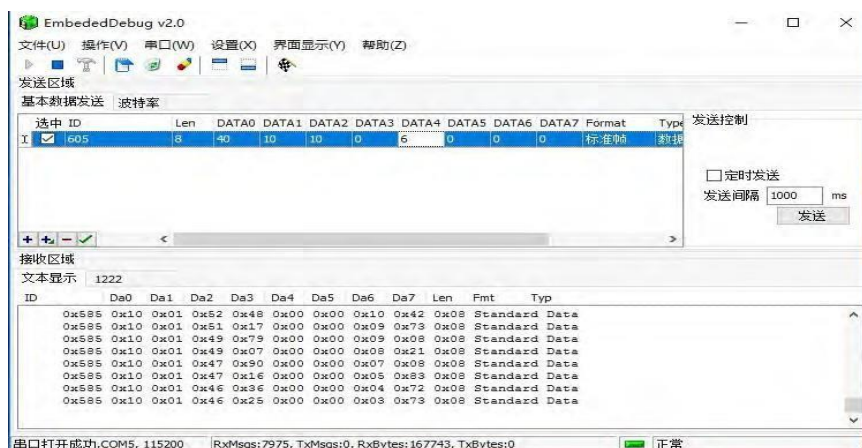
Order Information

Model	Communication Mode	Package Situation
BW-VG625	CAN	IP67/ Metal interface

Executive standard

- Specification for Static Calibration of Biaxial Inclination Sensors National Standard (Draft)
- GB/T 191 SJ 20873-2003 General Specification for Tiltmeters and Levels

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