BW-VG627 Series

Ultra High Accuracy Modbus Dynamic Inclination Sensor

Technical Manual

V3.0

BW-VG627

Ultra High Accuracy Modbus Dynamic

Introduction

The VG627 Dynamic Inclination Sensor product is an ultra-high accuracy attitude measurement device that measures the inertial attitude parameters of roll and pitch as well as angular velocity and acceleration of a moving carrier. Attitude deviations are estimated by a 6-state Kalman filter with appropriate gain for inclination measurements in motion or vibration.The VG627 utilizes high quality and reliable MEMS accelerometers and gyroscopes with algorithms to ensure accuracy, and a hermetically sealed design and rigorous workmanship to ensure that the product can accurately measure the carrier's attitude parameters even in harsh environments. The VG627 is equipped with digital interface, which can be easily integrated into the user's system.

Feature

- Dynamic accuracy: 0.05°
- Static accuracy: 0.01°
- Nonlinear compensation, quadrature compensation
- Special offset tracking algorithm to eliminate drift
- RS232/485/TTL output optional
- Wide temperature range：-40℃~+85℃
- High-performance Kalman filter algorithm
- Small Size：L60 x W59 x H29（mm）

Application

- Marine vessels
- Construction Machinery
- Platform stability
- Agricultural machinery
- ROV underwater robot navigation
- Unmanned Drive
- Robot
- Unmanned Craft

Feature

Electrical indicators

Voltage	9-36V DC
Working current	30mA （40mA Max）
Temperature in use	-40~85℃
Temperature in store	-55~100℃

Performance Index

Attitude Parameter	Dynamic Accuracy	0.05°
	Static Accuracy	0.01°
	Resolution	0.01°
	Tilt range	Pitch ± 90º, Roll ± 180º
Physical properties	Dimension	L60×W59×H29(mm)
	Weight (with cable)	280g
	Weight (with package)	360g
Interface characteristics	Start-up delay	<50ms
	Maximum Output Frequency	500Hz
	Serial Communication Rate	2400 to 115200 baud rate
	Digital Output Format	Binary High Performance Protocol
Average Trouble-Free Operating Time	≥ 30,000 hours	
electromagnetic compatibility	In accordance with GBT17626	
electrical insulation resistance	≥ 100 megohms	
impact resistance	2000g, 0.5ms, 3 times/axis	

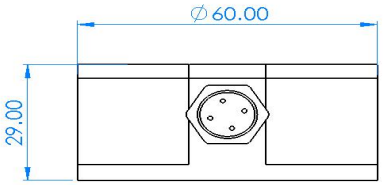
Resolution: The smallest change in the measured value that the sensor can detect and distinguish within the measurement range.
Accuracy: The root mean square error between the actual angle and the angle measured by the sensor for multiple times (≥16 times).

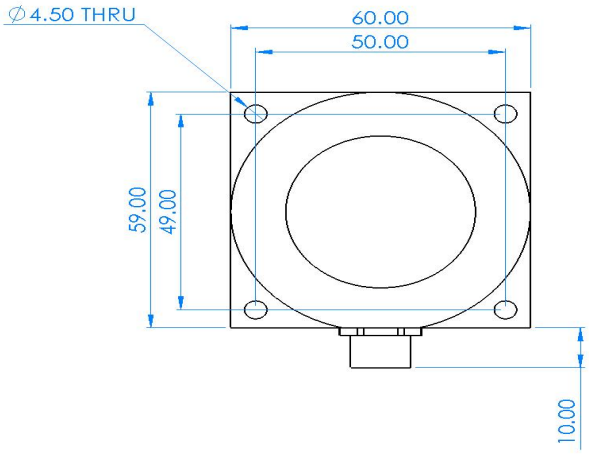
Mechanical properties

Connector	Metal interface（Cable 1.5m)
Protection level	IP67
Shell material	Magnesium aluminum alloy oxidation
Installation	Four M4 screws

Package product size

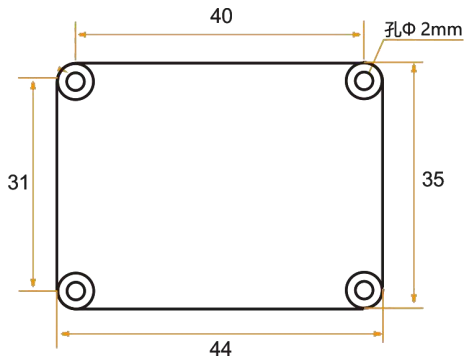
Product Size：L60*W59*H29（mm）





Bare board product size

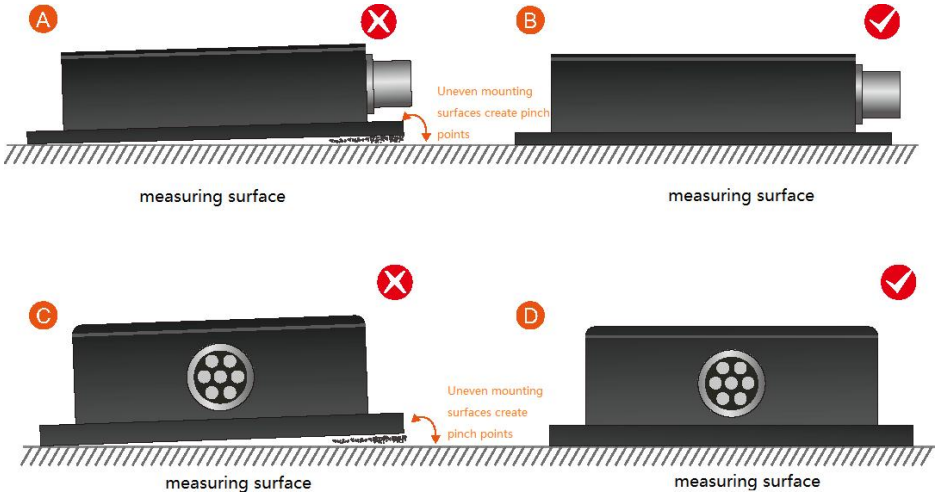
Product Size：L44*W35*H11（mm） The length and width may have an error of ±1mm, please refer to the actual product



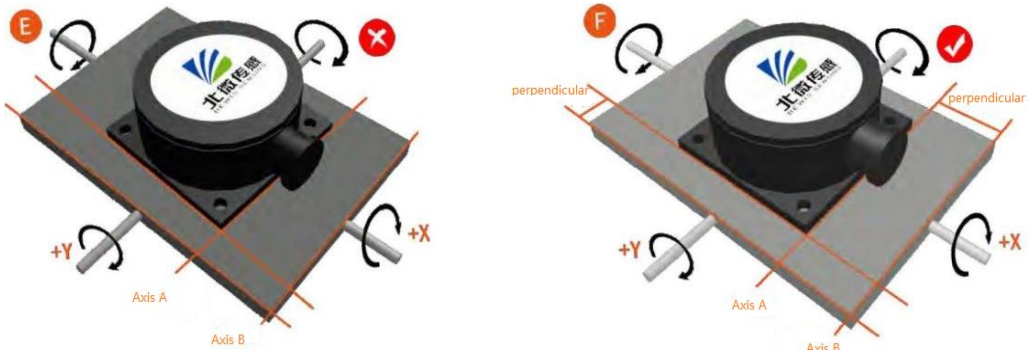
Installation

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible. There should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.



Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.

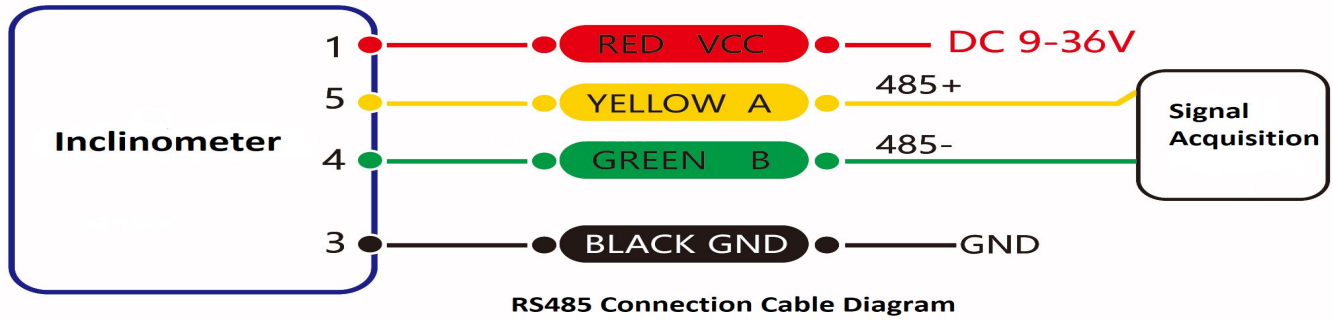


Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.

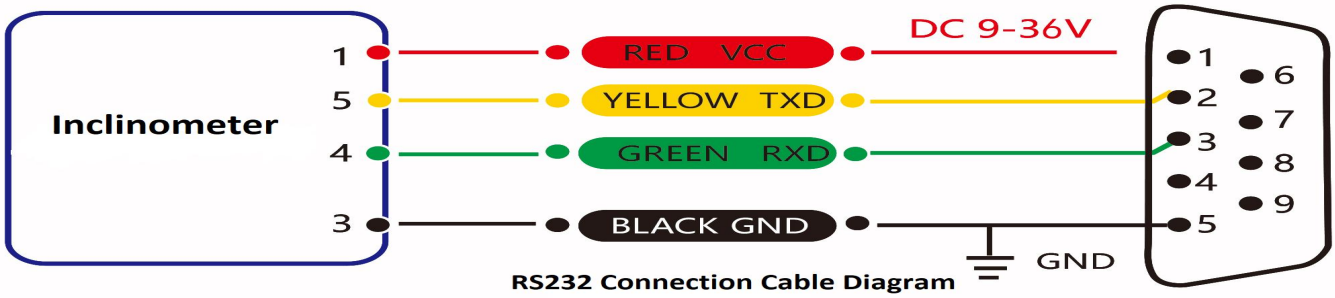
Electrical Interface

Wiring definition

Line Color	红色 RED	蓝色 BLUE	黑色 BLACK	绿色 GREEN	黄色 YELLOW
Function	1	2	3	4	5
	VCC DC 9-36V	NC	GND	Receive RXD (B、D-)	Send TXD (A、D+)



RS485 Connection Cable Diagram



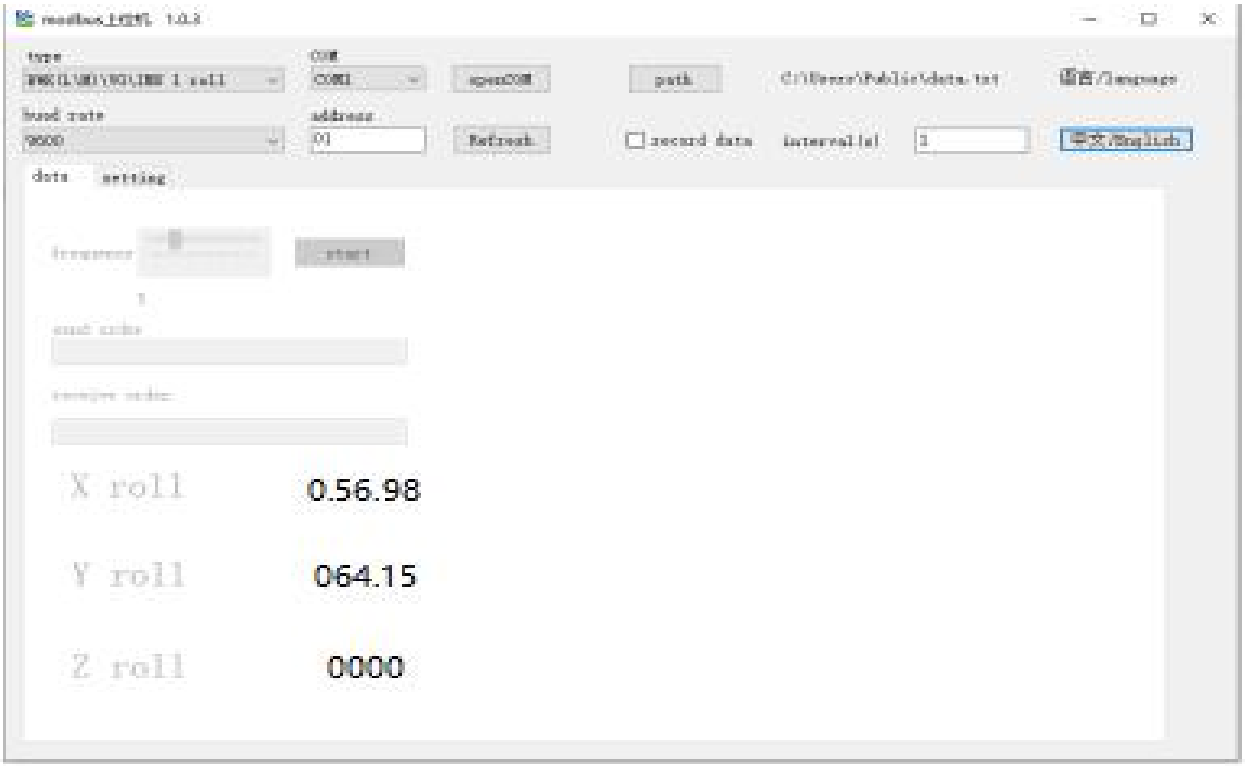
RS232 Connection Cable Diagram

Testing software

You can download the serial debugging assistant directly on the official website (technical service -> download area), or you can use the more convenient and intuitive host computer software. The BW-VG327 supporting serial port debugging software can connect the inclination sensor on the computer to display the angle. The software debugging interface is shown in the figure below. Using the tilt angle to debug the host computer, you can easily display the current X and Y directions, and you can also modify and set other parameters.

Step:

① Connect the serial port hardware of the inclinometer correctly, and connect the power supply.
② Select correct device Type (Select Azimuth series).
③ Select computer serial port and baud rate and click connect serial port.
④ Click start button and the current inclination Angle of the incliner in X and Y directions will be displayed on the screen.



Order Information

Model	Communication mode	Package situation
BW-VG627-485	RS485	IP67/ Metal interface
BW-VG627-232	RS232	IP67/ Metal interface
BW-VG627-TTL	TTL	IP67/ Metal interface

Executive standard

- Specification for Static Calibration of Biaxial Inclination Sensors National Standard (Draft)
- GB/T 191 SJ 20873-2003 General Specification for Tiltmeters and Levels

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Wuxi Bewis Sensing Technology LLC

Add：Building 30, NO. 58, Xiuxi Road, Binhu District,
Wuxi City, Jiangsu Province, China

Tel：+86 18921292620

Mail：sales@bwsensing.com

Web：www.bwsensing.com